

Minimizers of Interaction Energies

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RICAM, December 2014

Outline

- 1 **Deterministic Particle Methods for Diffusions**
 - Γ -Convergence
 - Numerical Scheme and Simulations
- 2 **Macroscopic Models: Repulsive-Attractive Potentials**
 - Steady States - (Local) Minimizers
 - Local Minimizers: Dimensionality of the support
 - Minimizers for Repulsive-Attractive Potentials
- 3 **Conclusions**

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Internal Energy

$E: \mathcal{P}(\mathbb{R}^d) \rightarrow \mathbb{R} \cup \{-\infty, +\infty\}$ by

$$E(\rho) = \begin{cases} \int_{\mathbb{R}^d} U(\rho(x)) \, dx & \text{if } \rho \in \mathcal{P}_{\text{ac},2}(\mathbb{R}^d) \\ +\infty & \text{otherwise} \end{cases},$$

where $U: [0, \infty) \rightarrow \mathbb{R}$ is the density of *internal energy* satisfying $U(0) = 0$.

Let us consider N particles in \mathbb{R}^d denoted by $x_N := (x_{1,N}, \dots, x_{N,N}) \in \mathbb{R}^{Nd}$, where N is a positive integer. For all $i \in \{1, \dots, N\}$, let us write $B_{i,N} := B(x_{i,N}, R_{i,N})$ the open ball of centre $x_{i,N}$ and radius

$$R_{i,N} = \frac{1}{2} \min_{j \neq i} |x_{i,N} - x_{j,N}|.$$

For these N particles consider

$$\rho_N = \frac{1}{N} \sum_{i=1}^N \frac{1}{|B_{i,N}|} \chi_{B_{i,N}},$$

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Approximated Internal Energy

Given

$$\mathcal{A}_N(\mathbb{R}^d) = \left\{ \mu \in \mathcal{P}(\mathbb{R}^d) \text{ such that } \exists x_N \in \mathbb{R}^{Nd}, \mu = \delta_{x_N} \right\}.$$

The discrete energy $E_N: \mathcal{A}_N(\mathbb{R}^d) \rightarrow \mathbb{R} \cup \{-\infty, +\infty\}$ by

$$E_N(\mu) = \int_{\mathbb{R}^d} H \left(\frac{1}{N} \sum_{i=1}^N \frac{1}{|B_{i,N}|} \chi_{B_{i,N}}(x) \right) dx,$$

where $B_{i,N} = B(x_{i,N}, R_{i,N})$ with x_N satisfying $\mu = \delta_{x_N}$. Note that

$$|B_{i,N}| = C_d R_{i,N}^d = \frac{C_d}{2} (\min_{j \neq i} |x_{i,N} - x_{j,N}|)^d,$$

where $C_d = |B(0, 1)|$ is the volume of the unit ball in dimension d . We clearly have $E(\rho_N) = E_N(\mu)$.

Γ-Convergence Result

- Logarithmic Entropy: Given

$$E_N(\mu) = -\frac{1}{N} \sum_{i=1}^N \log \left(\frac{NC_d}{2^d} \left(\min_{j \neq i} |x_{i,N} - x_{j,N}| \right)^d \right),$$

then it Γ -converges in d_2 to the logarithmic entropy $E[\mu]$.

- Nonlinear Entropy: The same holds for

$$E_N(\mu) = \int_{\mathbb{R}^d} \frac{1}{(m-1)N^m} \left(\sum_{i=1}^N \frac{1}{|B_{i,N}|} \chi_{B_{i,N}}(x) \right)^m dx$$

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$$E(\rho) = \int_{\mathbb{R}^d} \frac{\rho^m(x)}{m-1} dx \quad \text{if } \rho \in \mathcal{P}_{ac,2}(\mathbb{R}^d).$$

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Discrete JKO scheme

For any N particles in \mathbb{R}^d , we denote their weights by $w = (w_1, \dots, w_N) \in \mathbb{R}^N$, which we assume to satisfy $\sum_{i=1}^N w_i = 1$ and $w_i \geq 0$ for all $i \in \{1, \dots, N\}$. For any such $w \in \mathbb{R}^N$, define

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where

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$$F(\tilde{\rho}) = \sum_{i=1}^N w_i \left(\frac{(x_i - \tilde{x}_i)^2}{2\Delta t} + \frac{(R_i - \tilde{R}_i)^2}{6\Delta t} \right) + E(\tilde{\rho}).$$

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Assuming that $\tilde{R}_i = R_i + o(1)$, we have

$$\frac{(R_i - \tilde{R}_i)^2}{6\Delta t} \ll \frac{(x_i - \tilde{x}_i)^2}{2\Delta t}.$$

Thus we can approximate the functional F as

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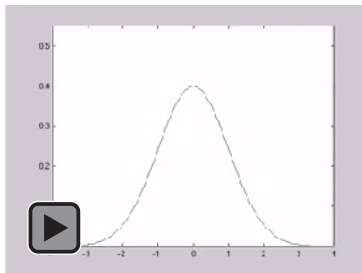
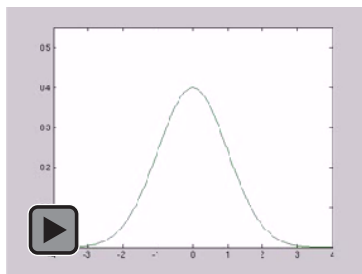
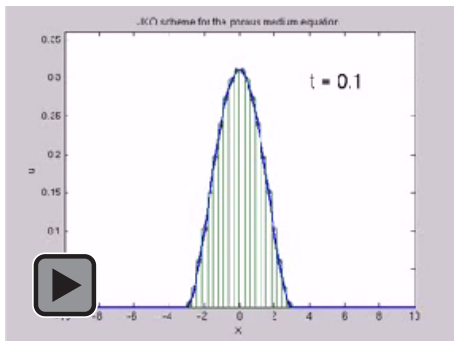
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Numerical Simulation: Heat and Fokker-Planck Equations



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Minimization of the Interaction Energy

Minimization Problem

We want to find local minimizers of the total interaction energy

$$\mathcal{F}[\mu] := \frac{1}{2} \iint_{\mathbb{R}^d \times \mathbb{R}^d} U(x-y) d\mu(x) d\mu(y).$$

in some set of probability measures $\mathcal{P}(\mathbb{R}^d)$.

What is the right topology to talk about measures being close?

Recurrent Question in many fields:

- Statistical Mechanics & Crystallization: Typically very singular potentials at zero: Lennard-Jones.
- Semiconductors - Astrophysics - Chemotaxis: Macroscopic model obtained from Vlasov Equation under certain limits. Newtonian Potential.
- Economic Applications: Mean Field Games, Cournot-Nash Equilibria.
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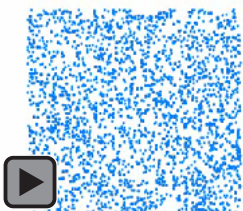
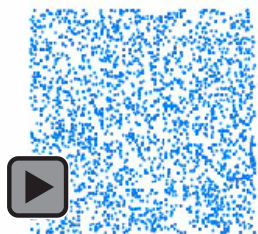
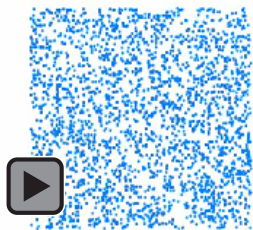
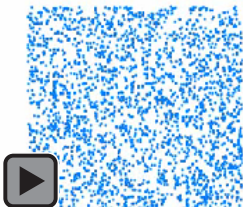
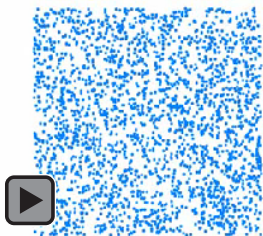
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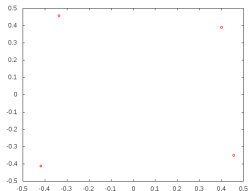
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Nontrivial patterns? - Particle Simulations

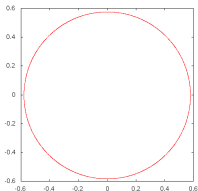


Summary: Particle Simulations $d = 2$

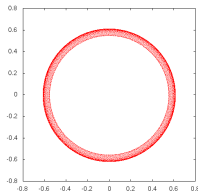
Potential $a = 4$,
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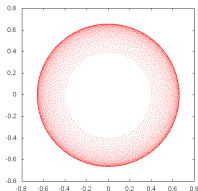
Potential $a = 4$,
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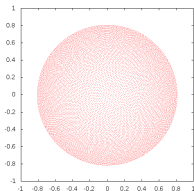
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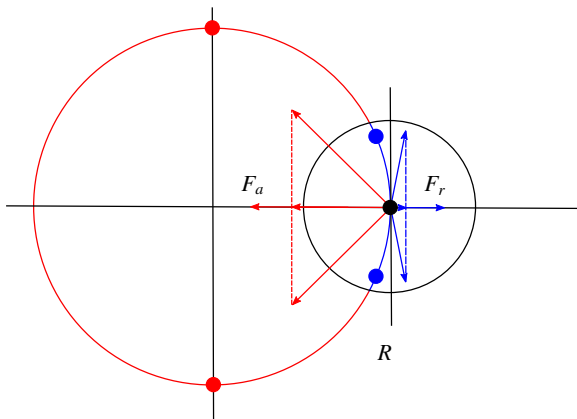
$$\dot{X}_i = - \sum_{j \neq i} m_j \nabla U(X_i - X_j)$$

$$U(x) = \frac{|x|^a}{a} - \frac{|x|^b}{b}$$

$$2 - d \leq b < a$$

Spherical shell

A **spherical shell** for some radius R is a stationary state for the aggregation equation for radial potentials.

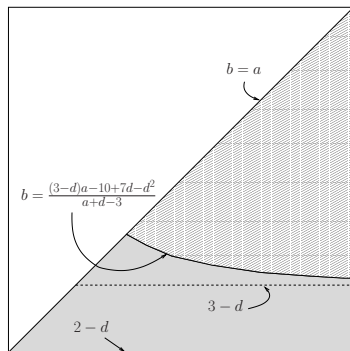


Power-Law Case

$$U(x) = \frac{|x|^a}{a} - \frac{|x|^b}{b} \quad 2 - d < b < a$$

Theorem: Ins/Stability of Delta Rings with respect to radial perturbations.

- There is a computable value of R such that the uniform distribution on the sphere of radius R , δ_R is a steady state.
- If the velocity field generated by δ_R is strictly increasing at R then it is unstable.
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(Balagué, C., Laurent, Raoul; Physica D 2013)

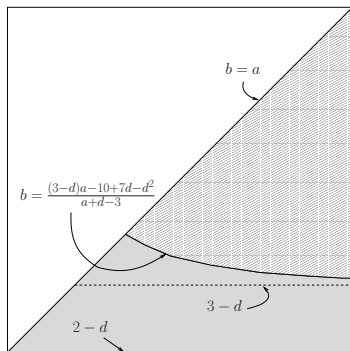
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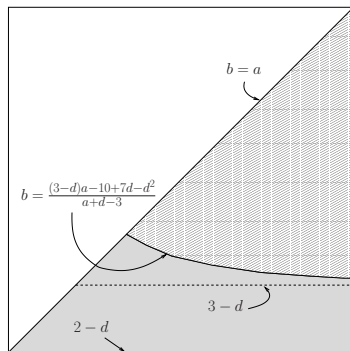
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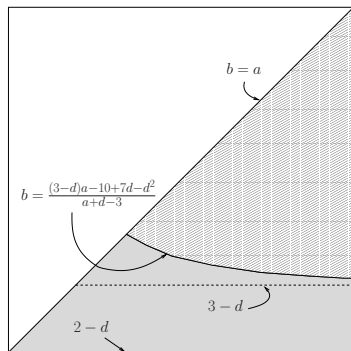
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W_∞ -Topology

The W_∞ -distance is defined as the optimal maximal mass displacement given by

$$W_\infty(\mu, \nu) = \inf_{\pi \in \Pi(\mu, \nu)} \sup_{(x, y) \in \text{supp}(\pi)} |x - y|,$$

- It is a good topology since it is closer to linearization around equilibrium of dynamical systems.
- It is the coarser topology among Wasserstein distances since all of them are ordered.
- Then, a local minimizer in W_2 is a local minimizer in W_∞ but not viceversa.

Basic Hypotheses:

(H1) U is a bounded from below lower semi-continuous function in $L^1_{loc}(\mathbb{R}^d)$.

W_∞ -Topology

The W_∞ -distance is defined as the optimal maximal mass displacement given by

$$W_\infty(\mu, \nu) = \inf_{\pi \in \Pi(\mu, \nu)} \sup_{(x, y) \in \text{supp}(\pi)} |x - y|,$$

- It is a good topology since it is closer to linearization around equilibrium of dynamical systems.
- It is the coarser topology among Wasserstein distances since all of them are ordered.
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W_∞ EL-Conditions

Assume that U satisfies (H1) and let μ be a local compactly supported minimizer of the energy $\mathcal{F}[\mu]$ in the W_∞ ball or radius ε . Then any point $x_0 \in \text{supp}(\mu)$ is a local minimum of $\psi = U * \mu$ in the sense that

$$\psi(x_0) \leq \psi(x) \text{ for a.e. } x \in B_\varepsilon(x_0).$$

Note that ε is uniform on the support of μ .

W_2 EL-Conditions

Under the same assumptions, if μ is a W_2 -local minimizer of the energy, then the potential ψ satisfy

- (i) $\psi(x) = (U * \mu)(x) = 2\mathcal{F}[\mu]$ μ -a.e.
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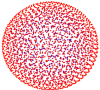



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Dimensionality of the support

Some simulations with power law potentials of the form

$$U(x) = \frac{|x|^a}{a} - \frac{|x|^b}{b}, \quad 2 - d < b < a$$

dim=3	dim=2	dim=2	dim=0
			
$b = -0.5$ $a = 5$	$b = 0.5$ $a = 23$	$b = 1.25$ $a = 15$	$b = 2.5$ $a = 5$

Local minimizers in 3D for different parameters when $b > -1$ increases. The computations were done with $n = 2,500$ particles.

Mild versus Strong Repulsive potentials

Support is essentially 0-dimensional for $b > 2$.

Let $U \in C^2(\mathbb{R}^N)$ be a radially symmetric potential which behaves like $-|x|^b/b$ in a neighborhood of the origin with $b > 2$.

Then a local minimizer of the interaction energy \mathcal{F} with respect to W_∞ cannot have a s -dimensional smooth components for any $1 \leq s \leq d$.

Dimension of the Support depends on $2 - d < b < 2$.

Assume that μ is a local minimizer of the interaction energy \mathcal{F} with respect to W_∞ such that U is radial with $U(x) \sim -|x|^b$ near zero and $2 - d < b < 2$. If μ contains s -Hausdorff dimensional connected components in its support, then $s > 2 - b$.

(Balagué, C., Laurent, Raoul; ARMA 2013)

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Outline

- 1 Deterministic Particle Methods for Diffusions
 - Γ -Convergence
 - Numerical Scheme and Simulations
- 2 Macroscopic Models: Repulsive-Attractive Potentials
 - Steady States - (Local) Minimizers
 - Local Minimizers: Dimensionality of the support
 - Minimizers for Repulsive-Attractive Potentials
- 3 Conclusions

Existence Global Minimizers

Non-HStable: Energy at infinity cost more than near the origin, i.e., the potential U satisfies

(H2) There exists $\mu \in \mathcal{P}(\mathbb{R}^d)$ compactly supported such that $\mathcal{F}[\mu] < 0$.

(H2) $\lim_{|x| \rightarrow \infty} U(x) \geq 0$.

Main Theorem

Assume that the radial potential U satisfies Hypotheses (H1), (H2), and is increasing outside a large ball. Then there exists a global minimiser for the energy \mathcal{F} . Furthermore, any such global minimiser has **compact support**.

(Cañizo, C., Patacchini; preprint 2014)

Main ideas: Uniform repartition of the mass over the support.

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By (H1) for R large enough:

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Euler-Lagrange: for ρ_R -almost all $z \in \text{supp} \rho_R$ we have

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Choose $A \in \mathbb{R}$ with $\frac{1}{2}U_{\min} \leq E_* < A < 0$ and $r' > 0$ with $U(x) \geq 2A$ for $|x| \geq r'$. Then for ρ_R -almost every z we have

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Examples

Power-laws & Morse Potentials

Consider the following potentials for all $x \in \mathbb{R}^d$ and $C_A, C_R, \ell_A, \ell_R > 0$:

(i) (*Power-law potential*) $U(x) = \frac{|x|^a}{a} - \frac{|x|^b}{b}$ with $-d < b < a$,

(ii) (*Morse potential*) $U(x) = C_R e^{-\frac{|x|}{\ell_R}} - C_A e^{-\frac{|x|}{\ell_A}}$ with either $\ell_A < \ell_R$ and $\frac{C_A}{C_R} < \left(\frac{\ell_R}{\ell_A}\right)^d$,

with the convention $\frac{|x|^0}{0} = \log |x|$.

Discrete To Continuum: Power-law Case

(C., Chipot, Huang; preprint 2014)

Discrete Setting: Find

$$I_N = \inf_{x \in (\mathbb{R}^d)^N} \mathcal{F}_N(x),$$

with

$$\mathcal{F}_N(x_1, \dots, x_N) = \sum_{i \neq j}^N \left(\frac{|x_i - x_j|^a}{a} - \frac{|x_i - x_j|^b}{b} \right).$$

Uniform Control of the support

Suppose that $1 \leq b < a$. Then the diameter of any global minimizer of \mathcal{F}_N achieving the infimum I_N is bounded independently of N .

Key Idea: use Euler-Lagrange and a convexity argument for the repulsive potential to estimate the distance between the two particles the furthest away.

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(H3) The function $U_a(x) := U(x) - V(x)$ with V being the Newtonian potential in dimension d satisfies:

$$\Delta U_a \in L^p_{loc}(\mathbb{R}^d) \quad \text{for some } p \in (d, \infty]$$

with ΔU_a bounded below.

Main Theorem

Assume that the potential U satisfies Hypotheses (H1) and (H3). Then **any μ compactly supported W_∞ local minimizer of the energy \mathcal{F} is bounded uniformly**, i.e., $\mu = \rho(x)d\mathcal{L}^d$ with $\rho \in L^\infty(\mathbb{R}^d)$.

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Assume that the potential U satisfies Hypotheses (H1) and (H3). Then **any μ compactly supported W_∞ local minimizer of the energy \mathcal{F} is bounded uniformly**, i.e., $\mu = \rho(x)d\mathcal{L}^d$ with $\rho \in L^\infty(\mathbb{R}^d)$.

(C., Delgadino, Mellet; preprint 2014)

Main ideas: Obstacle problems to obtain information out of the Euler-Lagrange conditions (Nash equilibria conditions).

It works for more-singular-than-Newtonian repulsion at the origin.

Regularity of Local Minimizers

(H3) The function $U_a(x) := U(x) - V(x)$ with V being the Newtonian potential in dimension d satisfies:

$$\Delta U_a \in L^p_{loc}(\mathbb{R}^d) \quad \text{for some } p \in (d, \infty]$$

with ΔU_a bounded below.

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Obstacle Problem

Continuity of the potential

Assume that the potential U satisfies Hypotheses (H1) and (H3). Let μ be a W_∞ local minimizer of E . Then the potential $\psi(x) := U * \mu(x)$ associated to μ is a **continuous function** in \mathbb{R}^N .

Implicit Obstacle Problem

For all $x_0 \in \text{supp}(\mu)$, the potential function ψ is equal, in $B_\varepsilon(x_0)$, to the unique solution of the obstacle problem

$$\begin{cases} \varphi \geq C_0, & \text{in } B_\varepsilon(x_0) \\ -\Delta\varphi \geq -F(x), & \text{in } B_\varepsilon(x_0) \\ -\Delta\varphi = -F(x), & \text{in } B_\varepsilon(x_0) \cap \{\varphi > C_0\} \\ \varphi = \psi, & \text{on } \partial B_\varepsilon(x_0), \end{cases}$$

where $C_0 = \psi(x_0)$ and $F(x) = \Delta U_a * \mu \in L^p_{loc}(\mathbb{R}^d)$. Furthermore, the density μ is given by

$$\mu = -\Delta\psi + F.$$

Particular Case: Newtonian repulsion and quadratic confinement, the global minimizer is the characteristic of a ball with unit mass upto translations.

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Conclusions

- The dimensionality of the support of local minimizers of the interaction energy can be classified in terms of the repulsion strength of the potential near zero.
- If the strength of the repulsion is stronger than or equal to Newtonian, they are bounded uniformly.
- Compactly supported global minimizers exist under the reasonable condition that it costs less energy to be near the origin than to be at infinity.
- References:
 - ① C.-Huang-Patacchini-Wolansky (work in preparation).
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